

where ΔU and φ is differential voltage and its phase shift

of ICT is not loaded and it is connected to the reference input of a lock-in amplifier. By the switching a switch to

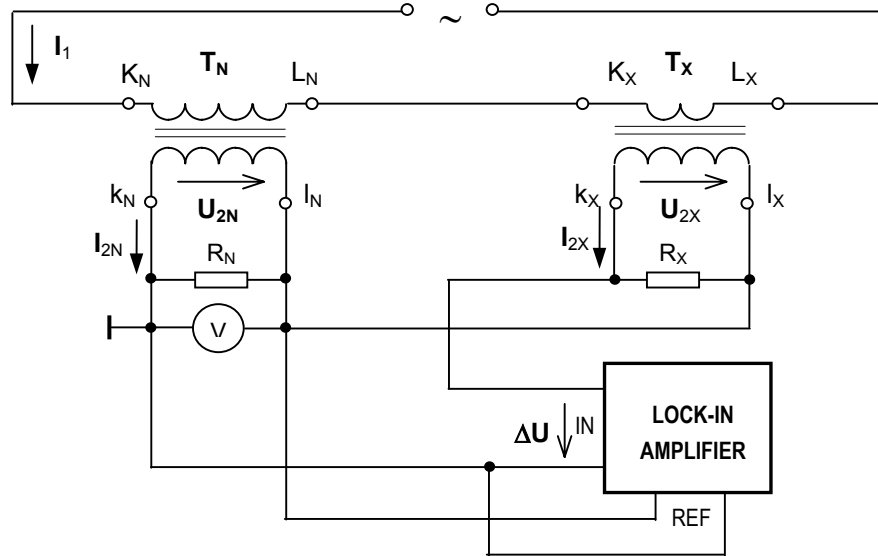


Fig.2. Principle of comparison method

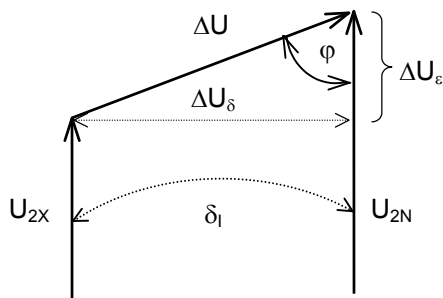


Fig.3. Part of phasor diagram

related to the voltage U_{2N} .

A lock-in amplifier on whose reference input is applied U_{2N} is used for their measurement. A character of the error ε_I will be determined from the sign of the phase shift φ so that the positive error corresponds plus sign of φ and conversely.

In a special case an indirect method according to Fig.4 can be used for ICT error determination. Secondary winding

position 1 the voltage U_i is brought on the lock-in amplifier input 1 and its magnitude will be determined from the formula

$$U_i = \frac{I_1}{p_1} \sqrt{(R_2 + R_B)^2 + X_B^2} \quad (5)$$

where U_i is secondary open-circuit voltage corresponding to the primary current I_1 , $p_1 = I_1/I_2$ is transformation ratio, R_2 is the resistance of ICT secondary winding N_2 , $R_B = B \cos \psi$ is real component of the burden B and $X_B = B \sin \psi$ is imaginary component of the ICT burden B , ψ je phase shift of burden.

The voltage U_i is adjusted by regulation of magnetizing current I_0 . After switching the switch to the position 2 the magnitude of the voltage U_0 , corresponding to the current I_0 , and its phase shift β are measured. If errors of tested ICT are small, then in the phasor diagram in Fig.5 $N_1 I_0 \ll N_1 I_1$ and $N_1 I_0 \ll N_2 I_2$ (N_1 and N_2 is number of primary and secondary

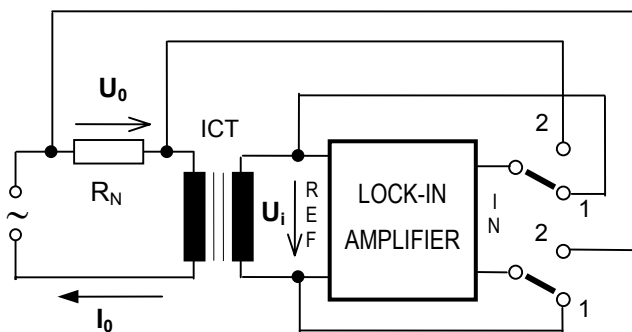


Fig.4. Principle of indirect method

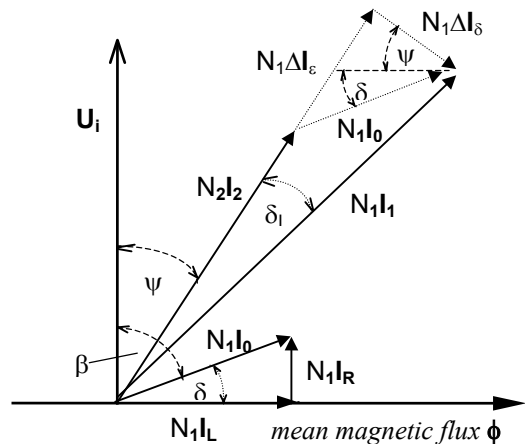


Fig.5. Phasor diagram

turns, I_1 and I_2 is primary and secondary current). So the ratio error and the phase displacement can be expressed as

$$\begin{aligned} \epsilon_I &= -\frac{N_1 \Delta I_\epsilon}{N_1 I_1} = -\frac{N_1 I_0}{N_1 I_1} \sin(\delta + \psi) = -\frac{U_0}{R_N I_1} \sin\left(\frac{\pi}{2} - \beta + \psi\right) \\ \delta_I &= \frac{N_1 \Delta I_\delta}{N_1 I_1} = \frac{N_1 I_0}{N_1 I_1} \cos(\delta + \psi) = \frac{U_0}{R_N I_1} \cos\left(\frac{\pi}{2} - \beta + \psi\right) \end{aligned} \quad (6)$$

This method can be used only for ICT, which does not have any error compensation. By adjusting of the voltage U_1 corresponding to the current I_1 according to (5) any influence of leakage inductance is not respected.

2. RESULTS OF MEASUREMENT

Errors of an ICT GOERZ type 4432 were measured by means of above mentioned methods. The transformation ratio of this ICT $p_1 = (0,2; 0,5; 1; 2; 5; 10; 20; 50$ and $100) A/0,05 A$. The rated burden is $B = 70 \Omega$ real and the DC resistance of secondary winding $R_2 = 20 \Omega$. Ratio error and phase displacement were measured for the transformation ratio $100 A/0,05 A$ and real burden 70Ω .

The current comparator Tettex 4764 with the set ratio $100 A/1 A$ served as a standard and the automatic transformer test set Tettex 2767 was used for error evaluation by the measurement performed according to the Fig.1. The on the test set adjusted transformation ratios were $I_{PX}/I_{SX} = 100 A/0,05 A$ and $I_{PN}/I_{SN} = 100 A/1 A$.

The current comparator Tettex 4764 with the set ratio $p_N = 100 A/5 A$ loaded with a standard resistor $R_N = 0,1 \Omega$ was used by the measurement method according to the Fig.2. The transformation ratio of the ICT under test was $p_X = 100 A/0,05 A$ and its secondary winding was loaded with a standard resistor $R_X = 10 \Omega$ connected serially with a resistor $R = 60 \Omega$ so that the total burden corresponded with the rated burden $R_B = 70 \Omega$. The values of R_N, R_X, p_N and p_X corresponded with the equation (2).

The error determination by means measurement of a no-load current was carried out according to the Fig. 3. Values of secondary voltage corresponding with the primary current were calculated according to (5) for $R_2 = 20 \Omega; R_B = 70 \Omega; X_B = 0$.

The lock-in amplifier Stanford Research SRS 830 was used for error measurement according to the Fig. 2 and 4. The error dependence was measured for (120; 100; 50; 20 and 10) % I_{1N} . The measured results are in Table 1.

TABLE I. Measurement results of ICT errors.

I_1 [% I_{1R}]	Method see Fig.1		Method see Fig.2		Method see Fig.4	
	ϵ [%]	δ [']	ϵ [%]	δ [']	ϵ [%]	δ [']
120	+0,012	-0,21	+0,013	-0,57	-0,113	-5,3
100	+0,012	-0,20	+0,013	-0,55	-0,111	-5,6
80	+0,012	-0,17	+0,014	-0,52	-0,109	-5,9
50	+0,011	-0,18	+0,016	-0,52	-0,105	-6,1
20	+0,011	-0,14	+0,021	-0,51	-0,104	-7,1

3. CONCLUSIONS

All described methods were used for ICT GOERZ type 4432 calibration for the transformation ratio $100 A/0,05 A$ and real burden 70Ω . By use of the transformer test set Tettex 2767 (see Fig.1) the secondary current rated value of the ICT under test was $0,05 A$. This value represents the minimum value of measured current and the test set operates with a reduced accuracy.

The method using standard resistors and lock-in amplifier (see Fig.2) provides a sufficient sensitivity in the full range of measured currents. This method required a precise ratio of used resistors because a measurement error depends on this ratio directly.

The indirect method (see Fig.4) can be used only for ICTs without any correction of ratio error and phase displacement. From the results in the Table 1 it is obvious that the ICT under test is corrected. The correction of ratio error is performed by means of a secondary winding modification, the phase displacement correction by means an inductance connected to an additional secondary winding.

The measured results according to the Fig.1 and 2 show good agreement corresponding with an uncertainty of used resistors.

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